

Cevahir Koprulu

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EDUCATION

University of Texas at Austin, Austin, TX, USA M.S. 2023, PhD 2026
Electrical and Computer Engineering GPA: 3.93/4
Interests: Reinforcement Learning (RL), Generalization, and Adaptation.

Bilkent University, Ankara, Turkey B.Sc. June 2021
Electrical and Electronics Engineering GPA: 3.73/4

Honours/Awards:

Bilkent University Comprehensive Scholarship
Scholarship of Turkish Prime Ministry
Bilkent University EEE Department High Honours
University Entrance Exam, Ranked 24th among 2 million students
FIRST Robotics Competition 2015: Recycle Rush, Rookie All-Star Award

WORK EXPERIENCE

Honda Research Institute - US Ann Arbor, MI
Research Intern (all work is under NDA) May 2024 - August 2024
Python, PyTorch, RAY

- Developed an **action advising framework**, GEN2SPEC, that leverages generalist agents to train specialist agents in a continual learning setting. This framework accelerates the training of an RL agent via action advice from a transformer-based meta-RL agent that can adapt to unseen tasks.

Eatron Technologies

Engineering Intern (all work is under NDA) Istanbul, Turkey
Python, C++, PyTorch, ROS June 2020 - June 2021

- Designed **graph convolutional** and **self-attention**-based neural network architectures to extract spatio-temporal features of a traffic scene for trajectory prediction in a Level-2+ ADAS powered vehicle.

ROKETSAN (in collaboration with Bilkent University)

Industrial Design Project (all work is under NDA) Ankara, Turkey
Python, C++, PyTorch, ROS Sept 2019 - June 2020

- Developed a mobile robot that follows a human leader, combining **YOLOv3 for object detection** and **artificial potential field method for path planning** in a mapped area with unknown dynamic obstacles.

RESEARCH WORK

Neural Stochastic Differential Equations for Uncertainty-Aware, Offline Reinforcement Learning ICLR, 2025

Cevahir Koprulu, Franck Djeumou, Ufuk Topcu

Safety Prioritizing Curricula for Constrained Reinforcement Learning ICLR, 2025

Cevahir Koprulu, Thiago D. Simão, Nils Jansen, Ufuk Topcu

Dense Dynamics-Aware Reward Synthesis: Integrating Prior Experience with Demonstrations Under Review

Cevahir Koprulu, Po-han Li, Tianyu Qiu, Ruihan Zhao, Tyler Westenbroek, David

Fridovich-Keil, Sandeep P. Chinchali, Ufuk Topcu

Joint Learning of Reward Machines and Policies in Environments with Partially Known

Semantics Artificial Intelligence,

Christos Verginis, Cevahir Koprulu, Sandeep Chinchali, Ufuk Topcu 2024

Risk-Aware Curriculum Generation for Heavy-tailed Task Distributions UAI, 2023

Cevahir Koprulu, Thiago D. Simão, Nils Jansen, Ufuk Topcu

Reward-Machine-Guided, Self-Paced Reinforcement Learning (Full Paper) UAI, 2023

Cevahir Koprulu, Ufuk Topcu

Reward-Machine-Guided, Self-Paced Reinforcement Learning (Extended Abstract) AAMAS, 2023

Cevahir Koprulu, Ufuk Topcu

Act to Reason: A Dynamic Game Theoretical Driving Model for Highway Merging Applications CCTA, 2021

Cevahir Koprulu, Yildiray Yildiz

TECHNICAL SKILLS

- Programming languages: (Expert) Python, (Proficient) C++, Julia
- Frameworks: PyTorch, JAX, TensorFlow, ROS, RAY

RELEVANT COURSEWORK

- **UT Austin:** Online Learning, Causality and Reinforcement Learning, Statistical Machine Learning, Learning-based Optimal Control, Game-Theoretic Modeling of Multi-Agent Systems, Program Synthesis, Cyber-Physical Systems, Reinforcement Learning, Convex Optimization, Probability and Statistics, and Complex Networks in the Real World.
- **École polytechnique fédérale de Lausanne** (Exchange - Spring 2019): Image Analysis and Pattern Recognition, Convex Optimization, Deep Learning, and Biological Modelling of Neural Networks.
- **Bilkent University:** Statistical Learning and Data Analytics, Robust Feedback Theory, Introduction to Financial Mathematics, Neural Networks, and Game Theory.

RESEARCH AND LEADERSHIP EXPERIENCES

Center for Autonomy

Ph.D. Student

Austin, TX
Aug 2021 - Ongoing

Systems Laboratory

Undergraduate Researcher

Ankara, Turkey
Sept 2019 - July 2021

- Developed **human driver models** from real-traffic data that can change its reasoning level dynamically by combining **level-k game theory** and **reinforcement learning**.

IEEE Robotics and Automation Society at Bilkent University

Chairman

Ankara, Turkey
May 2017 - June 2018

- Organized “Mühendis Kafası” in cooperation with Technology Development Foundation of Turkey: Series of sessions on Computer Vision and Deep Learning.
- Gave lectures on robotics, control techniques, and related micro-controller programming: EE-101: Introduction to Robotics with Arduino.

LANGUAGE SKILLS

- Turkish: Native proficiency
- English: TOEFL 110/120 (Fall 2020)
- French: DELF B1 (Spring 2015)

RECREATIONAL INTERESTS

I enjoy climbing, cycling, watching/playing soccer (football :)), and learning about history and psychology.